

Definition V, W two vector spaces.

We say V is isomorphic to W if there exists an invertible linear transformation $T: V \rightarrow W$. Such a linear transformation is called an isomorphism between V and W .

Theorem 2.19 V, W be finite dimensional.

Then V is isomorphic to W iff $\dim V = \dim W$

Corollary Any n -dimensional vector space is isomorphic to $\mathbb{F}^n$

Proof of 2.19 " $\Rightarrow$ " V isomorphic to $W \Rightarrow$ There exists $T: V \rightarrow W$
invertible

for any basis β in V , $T(\beta)$ is a basis for W

[β is lin ind $\Rightarrow T(\beta)$ is lin ind since T is 1-1 so $N(T) = \{0\}$]

$\beta = \text{span } V \Rightarrow T(\beta)$ spans $R(T) = W$ since T is onto

Moreover $|\beta| = |T(\beta)|$ since T is 1-1 so $\dim V = \dim W$
 $\dim V$ $\dim W$

" $\Leftarrow$ " If $\dim V = \dim W = n$, let $\{v_1, \dots, v_n\}$ be a (any) basis of V
and $\{w_1, \dots, w_n\}$ basis of W

Construct $T: V \rightarrow W$ by $T(v_j) = w_j$ and then extend it to V
by linearity.

One shows, T is one-to-one ($N(T)=0$) and T is onto ($R(T)=W$) or, alternately, one constructs a linear tr. $U: W \rightarrow V$ such that $UT = I_V$, $TU = I_W$ by $U(w_j) = v_j$ and extend it by linearity. This means T is invertible, hence an isomorphism. $\square$

Let $V \cong n$ -dimensional vector space, $\beta = \{v_1, \dots, v_n\}$ ordered basis in V .

$$\phi_\beta: V \rightarrow \mathbb{F}^n$$

$\phi_\beta(v_i) = e_i$
and extend by linearity
 $\{e_1, \dots, e_n\}$ standard ordered basis in $\mathbb{F}^n$

is an isomorphism $\Rightarrow \phi_\beta(v) = [v]_\beta$ (coordinate vector!)
is called the standard representation of V with respect to β

V, W two finite dim vector spaces $\dim V = n$
 $\dim W = m$

$\beta =$ basis for V
 $\gamma =$ basis for W

Then

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \phi_\beta \downarrow & \curvearrowright & \downarrow \phi_\gamma \\ \mathbb{F}^n & \xrightarrow{L_A} & \mathbb{F}^m \end{array} \quad A = [T]_{\gamma}^{\beta}$$

$$T = \phi_\gamma^{-1} L_A \phi_\beta \quad \text{or} \quad \phi_\gamma T = L_A \phi_\beta$$

Change of Bases

Matrix representation of a linear transformation $T: V \rightarrow V$ depends on the basis chosen. How does this matrix change when we change the basis?

Say β is a basis for V , $\beta = \{v_1, \dots, v_n\}$.

Recall $[T]_{\beta} = (a_{ij})$ where $Tv_j = \sum_{i=1}^n a_{ij} v_i$, $j=1, \dots, n$

Now let β' a different basis for V $\beta' = \{v'_1, \dots, v'_n\}$

Theorem: Given two bases β, β' for V , there exists an invertible matrix $Q \in M_{n \times n}$ such that

$$[T]_{\beta'} = Q^{-1} [T]_{\beta} Q$$

Proof: let $\beta = \{v_1, \dots, v_n\}$ and $\beta' = \{v'_1, \dots, v'_n\}$

Then for each $j=1, \dots, n$, $v'_j = \sum_{i=1}^n v_i a_{ij}$

a is more explicit notation
$$\begin{matrix} [v'_1 \dots v'_n] = [v_1 \dots v_n] \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \\ \text{"row order"} \quad \text{row order} \end{matrix}$$

We define $Q = [a_{ij}]$

Notice that $Q = [I_V]_{\beta'}^{\beta}$ and is invertible since $I_V: V \rightarrow V$ is the identity map

Now we prove $Q[T]_{\beta'} = [T]_{\beta} Q$.

Indeed $Q[T]_{\beta'} = [I_V]_{\beta'}^{\beta} [T]_{\beta'} = [I_V T]_{\beta'}^{\beta} = [T I_V]_{\beta'}^{\beta} = [T]_{\beta} [I_V]_{\beta'}^{\beta} = [T]_{\beta} Q$

Since Q^{-1} exist $\rightarrow$

$$[T]_{\beta'} = Q^{-1} [T]_{\beta} Q$$

$Q: \beta \rightarrow \beta'$ is called the change of basis matrix from β to β' .

Ex: $V = \mathbb{R}^2$, $T\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 3a-b \\ a+3b \end{pmatrix}$

$$\alpha = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \rightarrow [T]_{\alpha} = \begin{pmatrix} 3 & -1 \\ 1 & 3 \end{pmatrix}$$

$$\beta = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\} \rightarrow [T]_{\beta} = ?$$

$$T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \end{pmatrix} = a\begin{pmatrix} 1 \\ 1 \end{pmatrix} + b\begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \begin{cases} a+b=2 \\ a-b=4 \end{cases} \Rightarrow \begin{matrix} a=3 \\ b=-1 \end{matrix}$$

$$T\begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ -2 \end{pmatrix} = c\begin{pmatrix} 1 \\ 1 \end{pmatrix} + d\begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \begin{cases} c+d=4 \\ c-d=-2 \end{cases} \Rightarrow \begin{matrix} c=1 \\ d=3 \end{matrix}$$

$$\text{So } [T]_{\beta} = \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix} + [T]_{\alpha}$$

$$\beta' = \left\{ \begin{pmatrix} 2 \\ 4 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\}, [T]_{\beta'} = ?$$

$$T\begin{pmatrix} 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 2 \\ 14 \end{pmatrix} = a\begin{pmatrix} 2 \\ 4 \end{pmatrix} + b\begin{pmatrix} 3 \\ 1 \end{pmatrix} \Rightarrow \begin{matrix} a=4 \\ b=-2 \end{matrix}$$

$$T\begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 8 \\ 6 \end{pmatrix} = c\begin{pmatrix} 2 \\ 4 \end{pmatrix} + d\begin{pmatrix} 3 \\ 1 \end{pmatrix} \Rightarrow \begin{matrix} c=1 \\ d=2 \end{matrix}$$

$$\text{So } [T]_{\beta'} = \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix}$$

Now we show that $[T]_{\beta'} = Q^{-1} [T]_{\beta} Q$, where Q is the change of basis matrix from β to β' .

$$\beta^1 = \left\{ \begin{pmatrix} 2 \\ 4 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\} \Rightarrow \begin{pmatrix} 2 \\ 4 \end{pmatrix} = a \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b \begin{pmatrix} 1 \\ -1 \end{pmatrix} \rightarrow \begin{cases} a+b=2 \\ a-b=4 \end{cases}$$

$$a=3 \Rightarrow b=-1$$

$$\begin{pmatrix} 3 \\ 1 \end{pmatrix} = c \begin{pmatrix} 1 \\ 1 \end{pmatrix} + d \begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \begin{cases} c+d=3 \\ c-d=1 \end{cases}$$

$$\Rightarrow c=2 \\ d=1$$

$$\Rightarrow Q = \begin{pmatrix} 3 & 2 \\ -1 & 1 \end{pmatrix}$$

Now verify: $Q[T]_{\beta^1} = [T]_{\beta} Q$

$$Q[T]_{\beta^1} = \begin{pmatrix} 3 & 2 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix} = \begin{pmatrix} 8 & 7 \\ -6 & 1 \end{pmatrix}$$

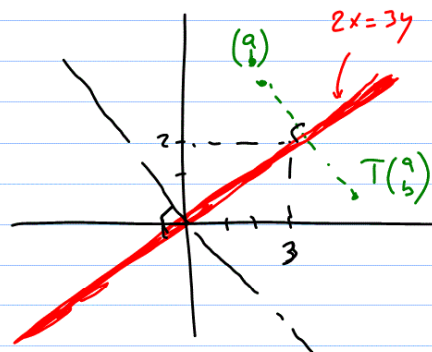
$$[T]_{\beta} Q = \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 3 & 2 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 8 & 7 \\ -6 & 1 \end{pmatrix}$$

match!

Ex: (Reflection about a line)

Consider the line $2x=3y$ in $\mathbb{R}^2$
and define $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ as in the figure

$T\begin{pmatrix} a \\ b \end{pmatrix}$ is the reflection of the point $\begin{pmatrix} a \\ b \end{pmatrix}$
relative to the line $2x=3y$



First, T is linear since this reflection preserves vector addition (given by the parallelogram rule) and scalar multiplication.

To find explicitly $T\begin{pmatrix} a \\ b \end{pmatrix}$, we consider the basis

$$\beta = \left\{ \begin{pmatrix} 3 \\ 2 \end{pmatrix}, \begin{pmatrix} -2 \\ 3 \end{pmatrix} \right\} \text{ . In this basis } T \begin{pmatrix} 3 \\ 2 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \\ T \begin{pmatrix} -2 \\ 3 \end{pmatrix} = \begin{pmatrix} 2 \\ -3 \end{pmatrix} \Rightarrow [T]_{\beta} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\text{Now let } \beta' = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \Rightarrow [T]_{\beta'} = Q^{-1} [T]_{\beta} Q$$

$$\text{where } Q: \beta' \rightarrow \beta \Rightarrow Q = \begin{pmatrix} 3 & -2 \\ 2 & 3 \end{pmatrix} \quad Q^{-1} = \frac{1}{13} \begin{pmatrix} 3 & 2 \\ -2 & 3 \end{pmatrix}$$

$$\text{So } [T]_{\beta'} = \frac{1}{13} \begin{pmatrix} 3 & 2 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 3 & -2 \\ 2 & 3 \end{pmatrix} \\ = \frac{1}{13} \begin{pmatrix} 3 & -2 \\ -2 & -3 \end{pmatrix} \begin{pmatrix} 3 & -2 \\ 2 & 3 \end{pmatrix} = \frac{1}{13} \begin{pmatrix} 5 & -12 \\ -12 & -5 \end{pmatrix}$$

$$\text{So } T \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} \frac{5a-12b}{13} \\ \frac{-12a-5b}{13} \end{pmatrix}.$$

Note: In the textbook, Q is called the change of coordinate matrix that changes β' -coordinates into β -coordinates. Here is why!

$$v \in V \Rightarrow v = a_1' v_1' + \dots + a_n' v_n' = [v_1' \dots v_n'] \begin{bmatrix} a_1' \\ \vdots \\ a_n' \end{bmatrix} = [v_1 \dots v_n] Q \begin{bmatrix} a_1' \\ \vdots \\ a_n' \end{bmatrix}$$

$$v = a_1 v_1 + \dots + a_n v_n = [v_1 \dots v_n] \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$$

$$\Rightarrow \boxed{Q \begin{bmatrix} a_1' \\ \vdots \\ a_n' \end{bmatrix} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}} \quad \text{or, in short } Q[v]_{\beta'} = [v]_{\beta}.$$

(see theorem 2.22)